

Automatic estimation of laryngeal vestibular closure duration using high resolution cervical auscultation (HRCA) signals

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Abstract

8 **Purpose:** Safe swallowing requires adequate protection of the airway to prevent
9 swallowed materials from entering the trachea or lungs (i.e., aspiration). Laryngeal
10 vestibular closure (LVC) is the first line of defense against swallowed material
11 entering the airway. Absent LVC or mistimed/shortened closure duration can lead
12 to aspiration, adverse medical consequences, and even death. Laryngeal vestibular
13 closure mechanisms can be judged commonly through the videofluoroscopic
14 swallowing (VFS) study, however, this type of instrumentation exposes patients to
15 radiation and is not available or acceptable to all patients. There is growing interest
16 in noninvasive methods to assess/monitor swallow physiology. In this study, we
17 hypothesized that our non-invasive sensor-based system, which has been shown to
18 accurately track hyoid displacement and upper esophageal sphincter opening
19 duration during swallowing, could predict laryngeal vestibular status, including the
20 onset of LVC and laryngeal vestibular re-opening (LVO) in real time and estimate
21 the closure duration with a comparable degree of accuracy as trained human raters.

22 **Methods:** The sensor-based system used in this study is high-resolution cervical
23 auscultation (HRCA). Advanced machine learning techniques enable HRCA signal
24 analysis through feature extraction and complex algorithms. A deep learning model
25 was developed with a dataset of 588 swallows from 120 patients with suspected
26 dysphagia and further tested on 45 swallows from 16 healthy participants. **Results:**

27 The new technique achieved an overall mean accuracy of 74.90% and 75.48%, for
28 the two data sets respectively, in distinguishing LVC status. Closure duration ratios
29 between automated and gold-standard human judgment of LVC duration were 1.13
30 for the patient data set and 0.93 for the healthy participant data set. **Conclusion:**
31 This study found that HRCA signal analysis using advanced machine learning
32 techniques can effectively predict LV status (closure or opening) and further
33 estimate LVC duration. HRCA is potentially a non-invasive tool to estimate LVC
34 duration for diagnostic and biofeedback purposes without x-ray imaging.

35 **Introduction**

36 Swallowing is a complex neuromuscular process involving the integration of
37 two distinct but related functions: airway protection and bolus transport. This
38 complex process involves volitional and reflexive neural activities paired with
39 coordinated contraction of many paired muscle groups. The result of this process is
40 specific biomechanical events, which are executed in a sequential temporal order to
41 ensure safe and efficient swallowing. Although there is variability within and among
42 humans, any disturbance of these biomechanical events caused by disease can lead
43 to swallowing disorders, known as dysphagia.

44 Entrance of food or liquid into the airway during the pharyngeal stage of
45 swallowing is known as aspiration. Aspiration is generally considered the most
46 concerning component of swallowing dysfunction and may lead to possibly fatal

47 pulmonary consequences, especially for individuals with neurologic and
48 neurodegenerative diseases (Cabib et al., 2016) or already-compromised
49 respiratory systems. Laryngeal vestibular closure (LVC) is usually considered the
50 primary and most critical aspect of laryngeal function during swallowing,
51 providing protection for the airway against the entrance of swallowed materials.
52 LVC is defined as the collapse of the laryngeal inlet via arytenoid adduction, and
53 arytenoid approximation to the epiglottis during epiglottic inversion (Logemann et
54 al., 1992). The closure of the laryngeal airway occurs in a peristaltic-like motion,
55 by a caudal to rostral compression while the larynx shortens facilitating
56 approximation of the epiglottis to the laryngeal inlet. This pattern of closure, which
57 is observable through videofluoroscopic studies (VFS) of swallowing function,
58 prevents airway invasion by closing off the airway while squeezing aberrant
59 swallowed material out of the laryngeal vestibule (LV) (Ekberg, 1982; Ekberg &
60 Nylander, 1982).

61 Timely and complete LVC is vital to safe and successful swallowing.
62 Incomplete closure, or shortened LVC duration may cause laryngeal penetration,
63 in which swallowed material enters the LV remains above the level of the vocal
64 folds, and/or tracheal aspiration of swallowed materials (Mann et al., 1999;
65 Robbins et al., 1993,). Shortened LVC duration is significantly associated with an
66 increased incidence of aspiration (Cabib et al., 2016). In fact, shortened LVC

67 duration is the primary impairment for predicting aspiration in patients following
68 stroke (Power et al., 2007).

69 The published literature reports a wide range of LVC durations, with mean
70 values from 0.31 to 1.07, depending on the presence or absence of certain factors
71 (Humbert et al., 2018; Logemann et al., 1992; Logemann et al., 2000; Logemann
72 et al., 2002; Molfenter & Steele, 2012; Ohmae et al., 1995; Ohmae et al., 1996;
73 Park et al., 2010). Prolonged LVC duration has been observed with increasing
74 bolus volumes, longer pharyngeal transit durations (Kang et al., 2010; Kendall et
75 al., 2003; Kim et al., 2005; Kim et al., 2010; Martin-Harris et al., 2003; Rofes et
76 al., 2010; Rosenbek et al., 1996), and during the performance of swallow
77 maneuvers such as the effortful swallow and the chin down posture (Hind et al.,
78 2001; Macrae et al., 2014; Young et al., 2015). Intentionally increasing LVC
79 duration during swallowing in patients with shortened LVC duration has been
80 investigated as a method of improving airway protection for decades. The
81 supraglottic swallow maneuver, described in 1993, was designed to volitionally
82 close the upper airway before swallowing in patients with a supraglottic
83 laryngectomy whose epiglottis had been resected (Mendelsohn & Martin, 1993).
84 This maneuver, and its sibling the super-supraglottic swallow, which exaggerates
85 contact between the arytenoids and epiglottic base in non-resected patients, has
86 been adapted for use in patients with dysphagia whose laryngeal anatomy remains

87 intact, and are mainstays of dysphagia compensatory management for many
88 patients (Lazarus et al., 1993). Many literatures demonstrated that healthy
89 individuals and individuals with dysphagia due to stroke could volitionally prolong
90 LVC after training (Azola et al., 2015; Lazarus et al., 1993; Macrae et al., 2014;
91 Mendelsohn & Martin, 1993; Young et al., 2015). Direct volitional control of the
92 timing and duration of LVC has enormous rehabilitation potential for individuals
93 with dysphagia.

94 VFS, a real-time dynamic x-ray technique, is the only standard instrumental
95 assessment to visualize LVC and to determine LVC duration during swallowing
96 (Martin-Harris & Jones, 2008). The duration of LVC is the measure of how long
97 the LV remains completely closed. In VFS images, complete LVC is defined as no
98 visible air space or barium contrast in the LV given complete contact of the
99 arytenoids to the base of the epiglottis and full epiglottic inversion over the base of
100 the arytenoids (Logemann et al., 1992). VFS can be used to train volitional
101 prolongation of LVC by providing patients with kinematic visual biofeedback.
102 However, VFS has inherent challenges such as patients' exposure to radiation.
103 Radiation safety standards limit exposure time during VFS, thus data collection
104 opportunities are time sensitive and despite its superior visualization of the entire
105 aerodigestive mechanism during swallowing, the use of VFS for visual
106 biofeedback during treatment to acquire compensatory volitional augmentation of

107 LVC is impossible. VFS may not be feasible in facilities without x-ray departments
108 and facilities may not have qualified clinicians to perform and interpret the VFS
109 images. Additionally, some patients may refuse x-ray testing or have other
110 conditions limiting its accessibility or feasibility (Bonilha et al., 2013;
111 Nierengarten, 2009; Steele et al., 2007; Zammit-Maempel et al., 2007).

112 Although acquiring temporal measurements of LVC duration would be
113 invaluable when managing many patients with dysphagia, it is rarely quantified
114 during imaging studies of swallowing function. During VFS studies, LVC is
115 typically judged as present, absent, or incomplete but temporal measurements are
116 not assessed.

117 There are limitations in a typical clinical setting that prevent frequent
118 temporal measurement of LVC, which result in these broad categorical
119 judgements. Swallow kinematic analysis using frame-by-frame review of VFS
120 images is not typically performed by clinicians because very few have the required
121 training or confirmation of their judgment reliability. Some clinicians may not have
122 the ability to record VFS images for secondary review due to lack of equipment or
123 limited access to archived materials. Additionally, a minimum temporal resolution
124 of 30 frames per second is required to properly assess LVC duration. Recording at
125 reduced frame rates (i.e., 7.5 or 15 frames per second), a common practice, is

126 inadequate for accurately capturing LVC timing due to its short duration (Bonilha
127 et al., 2013).

128 Adding temporal measures to the evaluation of LVC could provide clinicians
129 with objective swallowing kinematic data, which could be compared to published,
130 normative data, and provide clinical evidence of increased risk of airway
131 compromise (Humbert et al., 2018; Molfenter & Steele, 2012). Successfully
132 achieving this goal would help initiate appropriate compensatory interventions to
133 reduce dysphagia complications through timely diagnosis. The benefits of having
134 objective LVC data and the limitations of using VFS indicates that clinicians would
135 benefit from a non-invasive, alternative method to estimate LVC duration.
136 Naturally the ability to obtain LVC information noninvasively would revolutionize
137 efforts to stabilize or improve LVC timing and duration in people with dysphagia.

138 One potential non-invasive alternative for quantifying LV temporal
139 measures is high-resolution cervical auscultation (HRCA). Traditional cervical
140 auscultation (CA) is a method by which a clinician uses a stethoscope on a patient's
141 throat to assess swallowing and airway sounds. The cardiac analogy hypothesis
142 suggests that cervical auscultation acoustic signals are generated via vibrations
143 caused by valve and pump systems within the upper aerodigestive tract. As with
144 heart valves that open and close during the cardiac cycle, valves in the upper
145 aerodigestive tract produce characteristic acoustic signals during different stages

146 of swallowing (Cichero & Murdoch, 1998). However, the transmission of swallow
147 information may be incomplete due to the limited receiving bandwidth of a
148 stethoscope, and the interpretation of these sounds by judges listening through a
149 stethoscope can be bounded by the limits of the hearing frequency range of humans.
150 Likewise, numerous well-designed studies have confirmed the very low inter-judge
151 agreement for CA sounds rendering it a relatively weak diagnostic method (Leslie
152 et al., 2004). Therefore, CA cannot be considered a valid and reliable screening or
153 assessment tool for swallowing function due to imprecise and incomplete
154 interpretation of these signals (Sejdic et al., 2018).

155 HRCA exhibits unbiased and reliable interpretations as compared to
156 conventional CA assessment. HRCA uses high resolution accelerometers and
157 microphones, attached to patients' necks, to record vibratory and acoustic signals
158 during swallowing (Dudik et al., 2015; Movahedi et al., 2016). In line with the
159 cardiac analogy hypothesis, the striking of the epiglottis and arytenoids may be the
160 valve activity that generates swallowing sounds and vibrations during LVC, which
161 can be recorded with HRCA.

162 HRCA is an easily mobile, non-invasive tool, which is suitable for daily
163 monitoring of swallow function. Advanced technology using artificial intelligence
164 through machine learning techniques enables HRCA signal analysis by using
165 feature extraction and complex algorithms. HRCA has recently shown promise in

166 the autonomous detection of many swallow kinematic events. HRCA signals have
167 been found to be associated with hyoid bone displacement (He et al., 2019), LVC,
168 and the contact of the base of the tongue with the posterior pharyngeal wall (Kurosu
169 et al., 2019). Furthermore, HRCA successfully detected vertical and horizontal
170 displacements of the hyoid bone (Rebrion et al., 2018) and the diameter of upper
171 esophageal sphincter maximal opening (Shu, 2019). Given recent advances in
172 signal processing algorithms, HRCA could provide a fundamental contribution to
173 dysphagia management.

174 In this study we investigated the ability of advanced machine learning
175 techniques to predict LVC and LVO through HRCA signal analysis, thus allowing
176 a predicted estimation of LVC duration. We hypothesized that by analyzing HRCA
177 signals using machine learning techniques, we could predict LVC and LVO status
178 in real time and estimate the duration of LVC with a comparable degree of accuracy
179 as trained human raters. Successfully achieving this aim would significantly
180 improve LVC duration estimation by making it more automatic and objective.

181 **Methods**

182 **Data collection and equipment**

183 Two sets of data were collected; the first dataset was composed of 588
184 swallows from 120 enrolled patients with various diagnoses and etiologies of

185 dysphagia, the second was composed of 45 swallows from 16 healthy community
186 dwellers. Patient and healthy participant characteristics can be found in Table 1.

187 All patients and healthy participants underwent VFS at University of
188 Pittsburgh Medical Center Presbyterian Hospital. Since the aim of this study was
189 to investigate the feasibility of our system's ability to predict LVC regardless of
190 other variables, we intentionally did not control for patient variables including the
191 patient's diagnosis or characteristics of swallowed materials. Data for patients was
192 collected during routine clinical VFS studies, which resulted in various volumes
193 and consistencies of swallowed material. Healthy participants swallowed only thin
194 liquids of various volumes. All patient and healthy participants in this study signed
195 informed consents and the data collection protocol was approved by the
196 Institutional Review Board of the University of Pittsburgh.

197 **Please insert Table 1 here.**

198 VFSs for patients were conducted in the lateral plane using an x-ray machine
199 (Ultimax system, Toshiba, Tustin, CA) with a pulse rate of 30 fps. Healthy
200 participant data was collected in the lateral plane with a Precision 500D x-ray
201 system (GE Healthcare, LLC, Waukesha, WI) with a pulse rate of 30 fps. To ensure
202 that different resolutions did not affect judgment of kinematic events, we resampled
203 a subset of the original VFS data to match the sample rate of the new machine.
204 Five judges labeled nine swallowing kinematic events, including LVC and LVO,

205 using native and resampled resolutions. The level of agreement between human
206 labels at the different resolutions was excellent for all measures, with inter-judge
207 ICCs at or above .99. VFS videos were captured on an AccuStream Express HD
208 video card (Foresight Imaging, Chelmsford, MA) and digitized with a sampling
209 rate of 60 frames per second then saved to a hard disk using LabView's Signal
210 Express (National Instruments, Austin, Texas).

211 The sensor signals were collected concurrent to VFS examinations using a
212 tri-axial accelerometer neck sensor and contact microphone. The accelerometer
213 (ADXL 327, Analog Devices, Norwood, Massachusetts) was attached to the
214 midline of participant's anterior neck at the level of the cricoid cartilage with
215 surgical tape to obtain the best contact (Takahashi et al., 1994). The sensors' axes
216 were aligned to the anatomical directions of anterior-posterior [AP], superior-
217 inferior [SI], and medial-lateral [ML] respectively. The sensor was powered by a
218 power supply (model 1504, BK Precision, Yorba Linda, California) with a 3V
219 output, and the resulting signals were bandpass filtered from 0.1 to 3000 Hz and
220 amplified ten folds (model P55, Grass Technologies, Warwick, Rhode Island). The
221 microphone (model C411L, AKG, Vienna, Austria), which was powered by a
222 power supply (model B291, AKG, Vienna, Austria), was placed below the
223 accelerometer and slightly towards the right lateral side of the trachea. This
224 location has previously been described to be appropriate for collecting swallowing

225 sound signals without interfering with visualization of the proximal trachea or
226 larynx (Cichero & Murdoch, 2002; Takahashi et al., 1994). All signals acquired by
227 the accelerometer and microphone were fed into a National Instruments 6210 DAQ
228 and recorded at 20 kHz by the LabView program (Signal Express, National
229 Instruments, Austin, Texas). This setup has been shown to be effective at detecting
230 swallowing activity in previous studies (Dudik et al., 2016; Lee et al., 2010).

231 **Data labeling**

232 All videos were segmented into individual swallows. Swallow durations were
233 defined as the frame in which the head of the bolus reached the ramus of the
234 mandible (onset) to the frame in which the hyoid returned to its lowest position
235 following clearance of the bolus from the pharynx (offset). The corresponding
236 HRCA signals were also segmented according to the frames of onset and offset.
237 Reliability of segmentation was established on 10% of the videos with ICCs of over
238 .99 and intra-rater reliability and was maintained throughout testing to avoid
239 judgment drift.

240 Two trained raters labeled the first closure and first re-opening of the LV
241 from VFS x-ray videos for each swallow sample (Fig.3). Reliability was
242 established on 10% of the videos with ICCs of over .99 and intra-rater reliability
243 was maintained throughout testing to avoid judgment drift. The criteria in judging
244 the LV status are listed in Table 2.

245

Please insert Table 2 here.

246

Once the onset values for LVC and LVO were recorded by judges, the data

247

was entered into machine learning routines to enable training and testing of the

248

accuracy of the algorithms.

249

Deep neural network architecture, training, and testing

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An advanced hybrid deep neural network combining a Convolutional Neural

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Network and Recurrent Neural Network, called a Convolutional Recurrent Neural

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Network (CRNN), was used to build the relationship between the HRCA signals

253

and the LVC duration by predicting the LVC and LVO statuses. Artificial Neural

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Networks are loosely based on the neuronal networks in humans. They are typically

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organized in “layers” and contain “learning rules”, which allow the network to

256

recognize underlying patterns between input and output. The network is repeatedly

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trained based on observed datasets until it recognizes the patterns, and then the

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model is tested on a novel or “unseen” dataset to evaluate the model fit, or how

259

well the network has “learned”.

260

In this study, the two LV statuses (opened and closed) were coded as '0' and

261

'1' respectively. The human-labeled LV statuses were translated to the computer

262

program through this binary sequence (Fig. 1). The CRNN model was given the

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binary sequence for each swallow frame series (i.e. the first frame through the last

264

frame of the swallow), with the corresponding HRCA signal segments. The CRNN

265 was trained to mathematically model the relationship between the HRCA signals
266 and the LV statuses.

267 **Please insert Figure 1 here.**

268 A 10-fold cross validation technique was used to develop the CRNN model.
269 In 10-fold cross validation, all samples are divided into 10 non-overlapping training
270 groups. During training, nine of the ten groups are used to “train” the model by
271 providing feedback to help the model predict the human labels using signals only.
272 The remaining sample is used as a validation set to evaluate, or essentially help the
273 model find parameters (i.e. other factors), which may not have been identified
274 during training with the initial nine groups. This process is repeated a total of 10
275 times with each sample used as a validation set once.

276 For this study, the 588 patient swallowing samples were randomly divided
277 into 10 patient-specific training groups. In other words, an individual patient’s
278 swallows were contained within one group and not spread across any of the
279 remaining nine groups. The groups were used for training and validating the CRNN
280 to predict LVC and LVO based on HRCA signals alone. Once the 10-fold
281 validation was completed, the “unseen” dataset of 45 healthy participant swallows
282 was used as a testing set to evaluate the final model fit (i.e. to determine how well
283 the model could predict LVC and LVO using HRCA signals without having ever
284 “seen” the data) to evaluate how well the model generalized to new information.

305 mean overall accuracy for distinguishing LV status (opening and closure) from the
306 testing dataset of 45 healthy participant swallows was 75.48%.

307 Finally, to evaluate the model's predictive ability for LVC duration, we used
308 a duration ratio. The duration ratio was calculated as the predicted number of frames
309 for which the LV is closed over the human labeled LVC frames for which the LV is
310 closed. The closer the ratio is to 1, the closer the model's prediction was to the human
311 calculated duration. The duration ratio for the 10 patient validation groups is listed
312 in Table 3. The overall mean value for the duration ratio from the patient dataset was
313 1.13, indicating that the model slightly overestimated the number of frames in which
314 the LV was closed. The overall mean value for the duration ratio from the healthy
315 participant dataset was 0.93, indicating that the model slightly underestimated the
316 number of frames in which the LV was closed.

317

318 **Please insert Figure 3 here.**

319 **Please insert Table 3 here.**

320 **Discussion**

321 The primary aim of this study was to determine the feasibility of HRCA
322 signals to predict LV status (open, closed) during swallowing with an advanced
323 computer-aided approach, and thus non-invasively estimate the duration of LVC.
324 We demonstrated that a highly complex and non-linear relationship between the LV

325 status and HRCA signals can be established via advanced deep learning algorithms,
326 such as the proposed hybrid neural network in this study.

327 The CRNN model autonomously predicted LV status based on HRCA signal
328 input alone, independent from the manual analysis of the VFS videos by human
329 judges, which were used to assess the model’s performance. Our experimental
330 results revealed that the overall accuracy of the model to distinguish the LV status
331 (open, closed) was around 75% for both validation and testing datasets, suggesting
332 that the CRNN algorithm is capable of distinguishing LV status (open, closed) based
333 only on HRCA signals and, therefore, LVC duration.

334 The mean accuracies for machine predicted LVC and LVO frames for the
335 testing group of healthy participants’ “unseen data” were higher than the accuracies
336 for the training and validation sets of patient “seen data”, which underscores the
337 robustness of the CRNN model. It is unclear why the participant testing data had
338 larger mean error values than the patient data, but a possible explanation could be
339 differences between patient vs. healthy swallow kinematics. The algorithm was
340 trained and validated only on disordered swallows but was tested on healthy
341 swallows. Regardless, the higher accuracies seen in the tested set support the utility
342 of the algorithm; however, the system is not yet ready for clinical implementation.
343 This study established feasibility and illustrated the model’s relatively impressive
344 performance in accurately identifying very short-duration events. These events were

345 detected from among all events occurring during a swallow sequence. We intend to
346 hone the system's precision in future investigations.

347 HRCA also has the potential to be used as a non-invasive biofeedback tool
348 during swallowing rehabilitation. Dysphagia management is designed to target the
349 underlying biomechanical impairment during swallowing, which can be achieved
350 through behavioral modifications such as swallowing maneuvers. However, when
351 training swallowing maneuvers, patients are expected to exert volitional control over
352 laryngeal structures. This presents treatment challenges when imaging-based visual
353 biofeedback is unavailable because individuals with dysphagia may not be familiar
354 with laryngeal function. Providing the patients with extrinsic feedback could
355 improve patient compliance, accurate performance, and overall outcomes, as has
356 been demonstrated with other signal-based biofeedback methods (Martin-Harris et
357 al., 2017; Steele et al., 2012).

358 In clinical settings, the combination of clinician's verbal feedback with visual
359 biofeedback (i.e. kinematic feedback such as videofluoroscopy or FEES, or non-
360 kinematic such as signal waveforms, numerical data, or graphs) corresponding to the
361 patient's target movement can intensify the impact of extrinsic feedback (Crary &
362 Groher, 2000; Humbert & Joel, 2012). Unlike limbs, the volitional control of the
363 larynx is a relatively obscure act without externally observable activity upon which
364 to base motor learning. The amplified effect of combined extrinsic feedback may

365 augment the patient's intrinsic feedback system, which monitors the movement of
366 muscles, joints, and general body position, thus allowing the patient to make more
367 accurate approximations of targeted gross and fine movements (Abbruzzese et al.,
368 2014; Gandevia et al., 2002) and, ultimately, support learning the target task (Dayan
369 & Cohen, 2011; Taubert et al., 2011).

370 HRCA can provide biofeedback by estimating LVC and LVO, thereby
371 providing LVC duration to patients. Using HRCA in this way would limit radiation
372 exposure and could improve patient accuracy for targets related to LVC and LVO
373 onset and volitional LC prolongation, thus promoting better airway protection.

374 Methods of improving skill acquisition, along with schedules for dosage and
375 intensity, and reinforcement and feedback, are important components of
376 rehabilitation treatment taxonomies (Hart et al., 2019). Imagine, for example, there
377 is an HRCA visual biofeedback device, which provides the patient with a simple
378 visual representation of laryngeal closure and opening (e.g., red (open) or green
379 (closed) lights) as biofeedback. This type of system could provide the clinician and
380 patient with LVC duration information as well as provide the patient with visual
381 feedback during skill acquisition to help support them achieve their therapy goal.

382 HRCA provides an objective tool to noninvasively analyze laryngeal behavior
383 during swallowing, which can provide trackable outcome measures and help
384 demonstrate and document the efficacy of interventions to reduce aspiration risk.

385 The newly proposed machine learning technique using a CRNN model enabled us
386 to analyze HRCA signals associated with specific swallowing kinematic events
387 (LVC, LVO), and aligns with other research in our lab demonstrating the association
388 between HRCA signals and hyoid bone displacement (He et al., 2019), LVC, the
389 contact of the base of the tongue with the posterior pharyngeal wall (Kurosu et al.,
390 2019), and the diameter of upper esophageal sphincter maximal opening (Shu,
391 2019).

392 This new technique has potential for further non-invasive swallowing function
393 examination for other kinematic events such as tongue base retraction or epiglottic
394 inversion, which could not be completely perceived or precisely analysed
395 previously.

396 The aim of this study was to determine the ability of the sensors and the
397 CRNN to independently predict the LV status regardless of age, gender, or
398 diagnosis; however, these considerations provide interesting directions for future
399 research. Researchers could investigate systematic changes in model predictions of
400 LVC and LVO. Considerations for changes include varying bolus volumes and
401 consistencies, various patient characteristics (e.g. age, gender, diagnosis), and
402 disease characteristics (e.g. disease/dysphagia severity, infarct location from stroke,
403 and degenerative disease progression).

404 Further considerations for future research include exploring factors for
405 machine learning, such as model structure, learning algorithms, and hyperparameter
406 tuning. These factors may improve the accuracy of the CRNN model, thus ensuring
407 the identification of “safe” swallows and avoiding the over or under estimation of
408 LV closure. Ideally, clinical trials should investigate the efficacy of HRCA as a non-
409 invasive biofeedback tool to augment training in volitional laryngeal closure and to
410 establish its use as a swallowing intervention to reduce aspiration.

411 **Limitations**

412 One limitation of the current study is that the model was trained on patient
413 swallows and did not incorporate healthy swallows, which may have improved its
414 performance. These machine learning algorithms perform more robustly when they
415 are trained on heterogeneous exemplars (i.e., swallows) from the population under
416 investigation. We also conducted training and testing of the model with relatively
417 small sample sizes. Generally, larger training sample sizes are preferred in the
418 machine learning process. A larger sample of swallows would have increased the
419 opportunity for the model to characterize less common perturbations in swallow
420 physiology; the accuracy in modelling the novel test data subset would most likely
421 be improved. Our results are considered preliminary and will likely improve as we
422 increase the sample size and train the model with healthy swallows; however, this

423 study demonstrates the feasibility of using HRCA to predict LV status and LVC
424 duration.

425 **Conclusion**

426 This study found that HRCA signal analysis using an advanced machine
427 learning technique can effectively predict LV status (opening or closure) and
428 accurately estimate LVC duration. This provides a potential non-invasive tool to
429 estimate LVC duration for diagnostic and biofeedback purposes in managing
430 patients with dysphagia as an adjunct to x ray imaging.

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611 **Figure captions**

612 **Figure 1.** Illustrates using the temporal binary classification method to train the
613 CRNN architecture. The events of LVC and LVO were labeled by an experienced
614 rater in kinematic analysis of VFS videos. The numbers '0' and '1' represent the
615 opening and closure of LV respectively.

616 **Figure 2.** The frame error distribution for the validation results. The red bars
617 represent an error no larger than 3 frames. (a) & (b) show the distribution of onset
618 of LVC and onset of LVO respectively for the 10-fold validation dataset, which
619 contained 588 swallowing samples. (c) & (d) show the distribution of onset of LVC
620 and onset of LVO respectively for the testing dataset, which contained 45 unseen
621 swallowing samples.

622 **Figure 3.** The accuracy levels for the LV status prediction across the 10 validation
623 groups.